

COMMUNICATION ENHANCEMENT FOR INDIVIDUALS WITH SPEECH AND MOTOR IMPAIRMENTS USING FLEX SENSOR TECHNOLOGY

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Abstract : This Communication is a fundamental aspect of human interaction, allowing individuals to express thoughts, emotions, and needs. However, individuals with speech and motor impairments, such as dumbness or partial paralysis, face significant challenges in communicating effectively. Through extensive research and data analysis, it has been observed that approximately 1% of the global population, accounting for millions of individuals, experiences communication difficulties due to speech and motor impairments. These individuals often rely on non-verbal cues, gestures, or assistive technologies for communication. To overcome these limitations, our project introduces a communication system based on flex sensor technology. The flex sensor, a bend-sensitive device, is integrated into a wearable interface that individuals can easily attach to their limbs. By recognizing the number of bending counts of the flex sensor, the system translates these movements into predefined messages or symbols displayed on a digital interface. This approach allows individuals to express their thoughts and needs effectively, offering a more intuitive and accessible communication experience.

IndexTerms – Flex sensor, Gesture recognition, Bluetooth Module HC-05, LCD Module 16*2

I. INTRODUCTION

This project aims to address the communication challenges faced by individuals who are dumb or partially paralyzed. The project proposes a novel solution that utilizes flex sensor technology to recognize the number of bending counts of the sensor, enabling effective communication. By leveraging the capabilities of flex sensors, our project seeks to provide a reliable and accessible communication method for individuals with speech and motor impairments. This innovative approach offers a promising solution to enhance communication capabilities and improve the quality of life for this specific user group.

II. NEED OF THE STUDY

- Develop a hand gesture recognition system using flex sensors.
- Enable communication for individuals who are dumb or partially paralyzed.
- Utilize flex sensors to detect and interpret hand movements and gestures.
- Design and implement a microcontroller-based system for processing sensor data.
- Develop a gesture recognition algorithm to analyse sensor data and recognize specific hand gestures.
- Translate recognized gestures into text or predefined messages for communication.
- Create a user-friendly interface for interaction and customization of the system.
- Test the system with individuals who are dumb or partially paralyzed to assess performance and usability.
- Refine the system based on user feedback and document the design and implementation details.
- Consider ethical implications and privacy concerns throughout the project.

III. RESEARCH METHODOLOGY

3.1Components:

1. Bluetooth Module HC-05:

The HC-05 is a commonly used Bluetooth module in electronics projects. It allows wireless communication between devices using the Bluetooth protocol.

2. LCD Module 16*2:

The 16x2 LCD module is a widely used alphanumeric display module that consists of 16 columns and 2 rows, allowing you to display up to 32 characters at a time.

3. Arduino Nano:

The Arduino Nano is a compact and versatile development board based on the ATmega328P microcontroller. It shares many similarities with the Arduino Uno but comes in a smaller form factor. Here's a detailed description of the Arduino Nano:

Microcontroller: The Arduino Nano is built around the ATmega328P microcontroller, which operates at 5V. It has 32KB of flash memory for storing the program code, 2KB of SRAM for variables and data, and 1KB of EEPROM for non-volatile storage.

Digital and Analog I/O: The Arduino Nano provides a total of 14 digital I/O pins, of which 6 pins can be used as PWM (Pulse Width Modulation) outputs. Additionally, it has 8 analog input pins, which can also be used as digital I/O pins.

Serial Communication: The Arduino Nano supports serial communication via a built-in UART (Universal Asynchronous Receiver-Transmitter). It has dedicated RX (receive) and TX (transmit) pins for serial communication with other devices.

USB Interface: The Arduino Nano features a mini-USB port, which is used for programming the board and serial communication with a computer. It can be powered either through a USB or an external power supply.

Power Supply: The Arduino Nano can be powered using either a USB or an external power source. It has a built-in voltage regulator that can handle an input voltage range of 7-12V, making it suitable for a variety of power sources.

4. Flex Sensor:

A flex sensor, also known as a bend sensor or flex/bend sensor, is a type of sensor that measures the amount of bending or flexing applied to it. Flex sensors typically utilize a resistive material, such as carbon or conductive ink, which is embedded in the flexible strip. When the strip is straight or in its resting position, the resistance is at its maximum. As the strip bends, the resistance decreases proportionally to the degree of bending.

5. Switch:

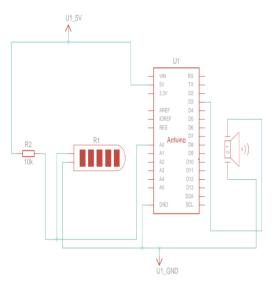
A switch is a fundamental electronic component that is widely used in various applications to control the flow of electrical current. It is a device that allows or interrupts the flow of electricity in a circuit.

3.2 Block diagram:

The Main System is provided through a 5V, 1A battery. The UNO Arduino receives this supply via a USB connection. The Arduino provides 5V supply to the flex sensor, Bluetooth module and display. The flex sensor gives analog voltage output corresponding to the movement of the

finger. To create a voltage divider circuit across the sensor, a 1k resistor is used. The 16-bit ADC on the UNO Arduino board receives the sensor's output as an input.

The digital output of the ADC is fed to the microcontroller of the UNO Arduino for single processing. The microcontroller compares input from the ADC and predefined value in the program. For the purpose of selecting a message that depends on flexibility, a switch is linked to the UNO Arduino port. Messages are shown by the movement made and subsequently output of the Arduino is sent to the LCD show for showing message in plain view. Further, it is also sent to the Bluetooth module thus the text to speech. application convert the text into audio.



3.2.1 block diagram

IV. RESULTS AND DISCUSSION

A flexible sensor is used to detect changes in resistance when a disabled person moves their finger. The sensor records these changes and converts them into electrical signals. These signals are then transmitted to Bluetooth modules that establish a wireless connection and send messages to a selected assistant or caregiver. It enables real-time communication and quick assistance to disable people, which increases their independence and safety.

For disabled people who have limited mobility but can move some body parts such as fingers, this project can greatly facilitate communication with an assistant or carer. With proper training and practice, a person can trigger a flex sensor with their finger movements, which in turn sends signals to Bluetooth modules. This technology opens new possibilities for effective and easy-to-use communication, allowing people with disabilities to express their needs and receive help more easily.

As part of the project, a system based on flex sensors was successfully implemented to detect finger movements of disabled people. Using an Arduino Nano microcontroller and a Bluetooth module, the system effectively transmitted these movements to the assistant or nurse through messages.

The project demonstrated the feasibility and potential benefits of using flexible sensors for assistive purposes. The ability to accurately detect finger movements opens possibilities for better communication and control for disabled people with limited mobility in their hands. By notifying caregivers in real time, the system enables quick help and support if needed.

V. FUTURE SCOPE

We can add multiple flex sensors to this project so that different fingers represent different commands, making it easier to use. Gesture recognition and extended functionality: Extend the system to recognize and interpret various finger movements and gestures beyond basic flexing. Use algorithms or machine learning techniques to recognize certain gestures, enabling more complex communication and control. Discover wireless options beyond Bluetooth. Consider using other protocols such as Wi-Fi, Zigbee or LTE-M to allow longer communication and seamless integration with other devices or smart home systems. Focus on making the system more accessible and affordable for more people. Conduct user tests and collect feedback from disabled people and their careers. This helps identify usability issues, improve the system based on real needs and ensure that the technology is truly useful and usable.

Research Through Innovation

VI. ACKNOWLEDGMENT

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