



# Algorithmic Approach for Solving Quadratic Fractional Programming Problem with Multiple Objectives

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**Abstract:** In the framework of this research, we propose a method to convert a multi-objective quadratic fractional programming problem (MOQFPP) into a single objective quadratic fractional programming problem (SOQFPP) using median of maximin and minimax technique. This can be demonstrated using a numerical example.

**Keyword:** Multi-objective quadratic fractional programming (MOQFP) and median of maximin and minimax.

**Introduction:** The Multi-Objective Quadratic Fractional Programming Problem (MOQFPP) is a quadratic limiting optimization problem with more than one objective functions. These objective functions are quantities that gauge the effectiveness of the system such as cost/profit, real cost/standard cost, output/employee cost/time, etc. MOQFP finds applications in various real-world scenarios including production planning, agricultural planning, healthcare management etc. In 1983, Chandra Sen [2] introduced the concept of multi-objective linear programming and outlined an approach for constructing multi-objective functions where optimal values of individual problems exceed zero. Sulaiman and Sadiq (2006) [6] investigated multi-objective functions using mean and median values. Subsequently, Najmaddin A. Sulaiman, Hamadameen and Abdul-Qader O. (2008) proposed a novel technique utilizing optimal averages ( $O_{AV}$ ) for functions, derived from modifications of Chandra Sen's and Sulaiman and Sadiq's approaches [3]. In 2013, Suleiman and Nawkhass [5] introduced an optimal average of maximin and minimax technique to convert MOQFPP into a single QFPP. Nahar Samsun et al. [1] introduced a harmonic average technique to optimize the objective function, synthesizing multiple objectives into a single function. Recently in 2021 Margia Yesmin and Md. Abdul Alim [7] presented an advanced transformation technique for addressing Multi-Objective Optimization Problems (MOOP).

In order to build on this research, we have created a Multi-Objective Quadratic Fractional Programming Problem (MOQFPP) and investigated the algorithm used to solve the Quadratic Fractional Programming Problem for multi-objective functions. The median of the maximin and minimax approaches are used in this algorithm. This can be explained with a numerical example.

**2. Quadratic Programming Problem (QPP):** Mathematical formulation of QPP is as follows:

$$\text{Max } Z \text{ or } \text{Min } Z = \delta + C^T X + \frac{1}{2} X^T G X \quad \text{or } (c_1^T X + \alpha)(c_2^T X + \beta)$$

subject to:

$$AX \leq b$$

$$X \geq 0$$

where,

- i)  $A$  is an  $m \times n$  matrix,
- ii)  $b$  is an  $m \times 1$  vector,
- iii)  $C, c_1, c_2$  and  $X$  are  $n \times 1$  vectors,
- iv)  $X^T$  is a transpose of  $X$ ,
- v)  $G$  is an  $n \times n$  symmetric square matrix and
- vi)  $\delta, \alpha$  and  $\beta$  are scalars.

**3. Quadratic Fractional Programming Problem (QFPP):** The mathematical formulation of QFP problem is as follows:

$$\text{Max } Z \text{ or } \text{Min } Z = \frac{(c_1^T X + \alpha_1)(c_2^T X + \alpha_2)}{(d_1^T X + \beta_1)}$$

subject to:

$$AX \leq b$$

$$X \geq 0$$

where,

- i)  $A$  is an  $m \times n$  matrix,
- ii)  $b$  is an  $m \times 1$  vector,
- iii)  $c_1, c_2, d_1$  and  $X$  are  $n \times 1$  vectors,
- iv)  $\alpha_1 \alpha_2$  and  $\beta_1$  are scalars,
- v)  $c_1^T, c_2^T$  and  $d_1^T$  are transpose of  $c_1, c_2$  and  $d_1$  respectively.
- vi)  $d_1^T X + \beta > 0$  and
- vii)  $S = \{X: AX \leq b, X \geq 0\}$  is non empty and bounded.

#### 4. Multi-Objective Quadratic Fractional Programming Problem (MOQFPP):

The Mathematical formulation of Multi-Objective Quadratic Fractional Programming Problem (MOQFPP) is:

$$\begin{aligned}
 \text{Max } z_1 &= \frac{(c_{11}^T X + \alpha_1)(c_{21}^T X + \beta_1)}{c_1^T X + \gamma_1} \\
 \text{Max } z_2 &= \frac{(c_{12}^T X + \alpha_2)(c_{22}^T X + \beta_2)}{c_2^T X + \gamma_2} \\
 &\vdots \\
 &\vdots \\
 \text{Max } z_r &= \frac{(c_{1r}^T X + \alpha_r)(c_{2r}^T X + \beta_r)}{c_r^T X + \gamma_r} \\
 \text{Min } z_{r+1} &= \frac{(c_{1r+1}^T X + \alpha_{r+1})(c_{2r+1}^T X + \beta_{r+1})}{c_{r+1}^T X + \gamma_{r+1}} \\
 &\vdots \\
 &\vdots \\
 \text{Min } z_s &= \frac{(c_{1s}^T X + \alpha_s)(c_{2s}^T X + \beta_s)}{c_s^T X + \gamma_s}
 \end{aligned} \tag{4.1}$$

subject to:

$$AX \leq b \tag{4.2}$$

$$X \geq 0 \tag{4.3}$$

where,

- i)  $A$  is an  $m \times n$  matrix,
- ii)  $b$  is an  $m \times 1$  vector,
- iii)  $C_i, c_{1i}, c_{2i}$  and  $X$  are  $n \times 1$  vectors, where  $i = 1, 2, 3, \dots, s$ ,
- iv)  $\alpha_i, \beta_i$  and  $\gamma_i$  are scalars, where  $i = 1, 2, 3, \dots, s$ ,
- v)  $C_i^T, c_{1i}^T$  and  $c_{2i}^T$  are transpose of  $C_i, c_{1i}$ , and  $c_{2i}$  respectively, where  $i = 1, 2, 3, \dots, s$
- vi)  $c_{1i}^T X + \alpha_i, c_{2i}^T X + \beta_i$  and  $c_i^T X + \gamma_i$  are positive for all feasible solutions, where  $i = 1, 2, 3, \dots, s$  and
- vii)  $S = \{X: AX \leq b, X \geq 0\}$  is non empty and bounded.

#### 5. Method for solving MOQFPP:

##### 5.1. Median of Maximin and Minimax Technique:

**Step1:** First of all, we will solve each objective function of (4.1) by using the modified simplex technique (MST) [4].

**Step2:** Next, we assign a name to the optimum/optimal value of each objective function  $\text{Max } z_i$  say  $\varphi_i$ , where  $i = 1, 2, \dots, r$  and  $\text{Min } z_i$  say  $\varphi_i$ , where  $i = r + 1, r + 2, \dots, s$ .

**Step3:** Choose  $m_1 = \min\{\varphi_i\}, \forall i = 1, 2, \dots, r$  and  $m_2 = \max\{\varphi_i\}, \forall i = r+1, \dots, s$  then calculate

$$\text{Md} = \text{Median} (\{m_j\}), \quad j = 1, 2$$

**Step4:** Optimize the combined objective function by using MST [4] with the same constraints (4.2) & (4.3) as:

$$\text{Max. } Z = \frac{(\sum_{i=1}^r \text{Max } z_i - \sum_{i=r+1}^s \text{Min } z_i)}{\text{Md}} \quad (5.1)$$

## 6. Numerical Example:

### Example 6.1.

$$\text{Max. } z_1 = \frac{(2x_1+x_2+1)(2x_1+x_2+2)}{(2x_1+2x_2+2)}$$

$$\text{Max. } z_2 = \frac{(4x_1+2x_2+2)(6x_1+3x_2+6)}{(3x_1+3x_2+3)}$$

$$\text{Max. } z_3 = \frac{(4x_1+2x_2+2)(6x_1+3x_2+6)}{(6x_1+6x_2+6)}$$

$$\text{Min. } z_4 = \frac{(-8x_1-4x_2-4)(6x_1+3x_2+6)}{(5x_1+5x_2+5)}$$

$$\text{Min. } z_5 = \frac{(-4x_1-2x_2-2)(10x_1+5+10)}{(2x_1+2x_2+2)}$$

Subject to:

$$x_1 + 2x_2 \leq 4, \quad 3x_1 + x_2 \leq 6$$

$$x_1, x_2 \geq 0$$

**Solution:** After computing the value of each individual objective function by using the modified simplex technique, the results are displayed in table 1:

Table 1

$i$	$z_i$	$x_i$	$\phi_i$	Md
1	5	(2,0)	5	14.5
2	20	(2,0)	20	
3	10	(2,0)	10	
4	-24	(2,0)	-24	
5	-50	(2,0)	-50	

Formulate the combined objective function as:

$$\text{Max. } Z = \frac{(\sum_{i=1}^r \text{Max } z_i - \sum_{i=r+1}^s \text{Min } z_i)}{\text{Md}} \quad \text{where } \text{Md} = \text{Median} (| m_j |), \quad j = 1, 2$$

$$\text{Max. } Z = \frac{(22x_1+11x_2+11)(18x_1+9x_2+18)}{(145x_1+145x_2+145)}$$

Subject to:

$$x_1 + 2x_2 \leq 4, \quad 3x_1 + x_2 \leq 6,$$

$$x_1, x_2 \geq 0$$

Hence, the optimal solution is:

$$\text{Max. } Z = 6.83, \quad x_1 = 2, \quad x_2 = 0.$$

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